

Thermal Expansion in a Constrained Elastic Cylinder

Abstract: The stress developed in an elastic cylinder of finite length undergoing thermal expansion with one end clamped is expressed in terms of a series expansion of a biharmonic function, appropriate derivatives of which give the displacements and stresses within the cylinder. The coefficients in this series are determined by a least-squares fit to the boundary conditions at the ends of the cylinder and values of the stress on various surfaces are found as functions of the height-to-radius ratio. All components of the stress tensor become infinite at the circumference on the clamped end. A tabulation is included of quantities of interest in any cylindrical problem in which the curved surface is a free surface.

Introduction

There has been considerable interest in the problem of stress induced by thermal shrinkage or expansion in an elastic body with one or more surfaces constrained. Such problems arise, for example, in the encapsulation of electronic circuit components. The calculation of these stresses in a circular cylinder is the subject of this paper. The cylindrical symmetry reduces the problem to a two-dimensional one, offering the possibility of a tractable solution in terms of a series of biharmonic functions. In previous work studies of rectangular plates have been carried out variationally¹ and studies of long bars (constrained on a long edge) have been made using series expansions.² The cylindrical geometry, although permitting solution of a three-dimensional problem in two-dimensional terms, leads to considerable mathematical complexity in the sense that the terms in the series for various stresses are not orthogonal and the coefficients must be found by solving a set of linear equations. Certain mathematical constants involved in the solution are independent of the dimensions of the cylinder and can be given as functions of the elastic moduli. A considerably more extensive tabulation of these quantities than has heretofore appeared³ is given here.

Theory

The problem is to determine the displacements and stresses in a cylinder of radius R and height h that undergoes thermal expansion with one end ($z = h$) clamped to a rigid, nonexpanding plate. The other end ($z = 0$) and the curved

surface or circumference ($r = R$) of the cylinder are free surfaces, i.e., no forces are applied.

Let u be the displacement of a point in the cylinder in the radial direction and w the displacement in the z direction. If we assume that all quantities are independent of the angular coordinate θ , the strains are

$$\begin{aligned} \epsilon_{rr} &= \frac{\partial u}{\partial r}, & \epsilon_{\theta\theta} &= \frac{u}{r}, & \epsilon_{zz} &= \frac{\partial w}{\partial z}, \\ \epsilon_{rz} &= \epsilon_{zr} = \frac{1}{2} \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial r} \right), & \epsilon_{r\theta} &= \epsilon_{z\theta} = 0 \end{aligned} \quad (1)$$

and the dilation is

$$\Delta = \epsilon_{rr} + \epsilon_{\theta\theta} + \epsilon_{zz} = \frac{\partial u}{\partial r} + \frac{u}{r} + \frac{\partial w}{\partial z}. \quad (2)$$

The cylinder temperature is assumed to be raised by a constant amount ΔT above the temperature at which no strain exists. If λ and μ are the Lamé constants at the elastically isotropic cylinder, in terms of which Young's modulus E and Poisson's ratio ν are expressed as

$$E = \mu(3\lambda + 2\mu)/(\lambda + \mu) \text{ and } \nu = \frac{1}{2}\lambda/(\lambda + \mu), \quad (3)$$

the stress-strain relations are⁴

$$\begin{aligned} T_{rr} &= 2\mu\epsilon_{rr} + \lambda\Delta - (3\lambda + 2\mu)\alpha\Delta T, \\ T_{\theta\theta} &= 2\mu\epsilon_{\theta\theta} + \lambda\Delta - (3\lambda + 2\mu)\alpha\Delta T, \\ T_{zz} &= 2\mu\epsilon_{zz} + \lambda\Delta - (3\lambda + 2\mu)\alpha\Delta T, \\ T_{rz} &= 2\mu\epsilon_{rz} \text{ and} \\ T_{r\theta} &= T_{z\theta} = 0, \end{aligned} \quad (4)$$

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where α is the linear coefficient of thermal expansion; there is a constant strain $\alpha\Delta T$ in each principal direction.

The equations of equilibrium are

$$\frac{\partial T_{rr}}{\partial r} + \frac{T_{rr} - T_{\theta\theta}}{r} + \frac{\partial T_{rz}}{\partial z} = 0 \quad (5a)$$

and

$$\frac{\partial T_{rz}}{\partial r} + \frac{T_{rz}}{r} + \frac{\partial T_{zz}}{\partial z} = 0. \quad (5b)$$

These are subject to the following boundary conditions: At $z = h$ (on the plate) the cylinder is constrained to have zero displacement, so that

$$u(r, h) = w(r, h) = 0; \quad (6a)$$

at $r = R$ and at $z = 0$ no forces are applied, so that

$$T_{rr}(R, z) = T_{rz}(R, z) = 0 \text{ and} \quad (6b)$$

$$T_{zz}(r, 0) = T_{rz}(r, 0) = 0. \quad (6c)$$

Love⁴ has shown that problems of cylindrical symmetry can be solved in terms of a single biharmonic function. For example, let

$$\nabla^4 \Phi \equiv \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{\partial^2}{\partial z^2} \right)^2 \Phi = 0 \quad (7)$$

and define the following expressions (which are equivalent, but not identical, to those given by Love):

$$u = -\frac{1}{2\mu} \frac{\partial^2 \Phi}{\partial r \partial z}, \quad (8)$$

$$w = \frac{1}{2\mu} \left(\frac{\lambda + 2\mu}{\lambda + \mu} \nabla^2 \Phi - \frac{\partial^2 \Phi}{\partial z^2} \right).$$

The stresses obtained in terms of Φ from Eqs. (4) using Eqs. (1) and (2) automatically satisfy the equilibrium conditions, Eqs. (5), and the present problem is reduced to constructing the function Φ that satisfies the boundary conditions given in Eqs. (6).

We begin this construction by expanding Φ in a series of solutions of the biharmonic equation (7), each term of which automatically satisfies the boundary conditions on the circumference of the cylinder. The coefficients in this series are adjusted so that the remaining boundary conditions are satisfied when the number of terms in the series becomes infinite; inasmuch as the terms in the series are nonorthogonal, this adjustment is made using a least-squares procedure. The coefficients of certain trivial solutions of the biharmonic equation are chosen so that the boundary conditions are satisfied in an average sense and it turns out that the trivial solutions included in Φ serve to remove the constant thermal stresses and to add a constant to the axial displacement w .

We define the reduced quantities

$$\begin{aligned} x &= r/R, \\ \zeta &= z/R, \\ l &= h/R, \end{aligned} \quad (9)$$

$$K^2 = \frac{\lambda + 2\mu}{\lambda + \mu} = 2(1 - \nu)$$

and write

$$\Phi = a_1 \zeta^2 + a_2 \zeta^3 + b_1 x^2 + b_2 x^2 \zeta + \eta(x, \zeta). \quad (10)$$

The first four terms are the trivial solutions of the biharmonic equation that are regular at $x = 0$ (the constant term and the term proportional to ζ have been omitted since they do not contribute to any displacements or stresses) and η represents the nontrivial part of Φ , which is still to be constructed. In terms of the coefficients a_1, a_2, b_1 and b_2 the displacements are

$$u = -\frac{b_2}{\mu R^2} x + \text{terms in } \eta,$$

$$\begin{aligned} w &= \frac{1}{R^2} \left\{ \frac{a_1}{\lambda + \mu} + \frac{2(\lambda + 2\mu)b_1}{\mu(\lambda + \mu)} \right. \\ &\quad \left. + \left[\frac{3a_2}{\lambda + \mu} + \frac{2(\lambda + 2\mu)b_2}{\mu(\lambda + \mu)} \right] \zeta \right\} + \text{terms in } \eta, \end{aligned}$$

where the "terms in η " are obtained from Eqs. (8) with Φ replaced by η .

• Evaluation of coefficients

The stresses all involve derivatives of u and w , so it is clear that the a_1 and b_1 terms in Φ contribute constants to w and appear nowhere else. Without loss of generality we can choose $b_1 = 0$ and use a_1 to fix the constant term in w . The terms in a_2 and b_2 produce a displacement field like that due to unconstrained thermal expansion, i.e., constant strains with no shear; they add constants to the principal stresses and do not affect the shear stress. The boundary conditions require that T_{rr} vanish on the circumference and that T_{zz} vanish on the free end ($z = 0$). It follows, then, that

$$\int_0^1 x T_{zz}(x, 0) dx = \int_0^1 T_{rr}(1, \zeta) d\zeta = 0. \quad (11)$$

We shall choose η in such a way that its contribution to $T_{rr}(x, \zeta)$ automatically vanishes when $x = 1$. It will then turn out that η makes no contribution to the average of T_{zz} over the free end; thus Eqs. (11) will contain no terms in η . To satisfy Eqs. (11), a_2 and b_2 must be chosen to remove the thermal stress term $-(3\lambda + 2\mu) \times \alpha \Delta T$ from T_{rr} and T_{zz} . In this way $T_{rr}(1, \zeta)$ is made identically zero for all ζ , while $T_{zz}(x, 0)$ presumably becomes

zero pointwise as the number of terms in the series for η becomes infinite. The required values of a_2 and b_2 are

$$a_2 = \frac{1}{3}R^3(3\lambda + 5\mu)\alpha\Delta T; \quad b_2 = -R^3\mu\alpha\Delta T. \quad (12)$$

The displacements and stresses now become⁴

$$\begin{aligned} u &= R\alpha\Delta T x - \frac{1}{2\mu} \frac{\partial^2 \eta}{\partial r \partial z}, \\ w &= R\alpha\Delta T(\zeta - l + B) \\ &\quad + \frac{1}{2\mu} \left(\frac{\lambda + 2\mu}{\lambda + \mu} \nabla^2 \eta - \frac{\partial^2 \eta}{\partial z^2} \right), \\ T_{rr} &= \frac{\partial}{\partial z} \left[\frac{\lambda}{2(\lambda + \mu)} \nabla^2 \eta - \frac{\partial^2 \eta}{\partial r^2} \right], \\ T_{\theta\theta} &= \frac{\partial}{\partial z} \left[\frac{\lambda}{2(\lambda + \mu)} \nabla^2 \eta - \frac{1}{r} \frac{\partial \eta}{\partial r} \right], \\ T_{zz} &= \frac{\partial}{\partial z} \left[\frac{3\lambda + 4\mu}{2(\lambda + \mu)} \nabla^2 \eta - \frac{\partial^2 \eta}{\partial z^2} \right], \\ T_{rz} &= \frac{\partial}{\partial r} \left[\frac{\lambda + 2\mu}{2(\lambda + \mu)} \nabla^2 \eta - \frac{\partial^2 \eta}{\partial z^2} \right], \end{aligned} \quad (13)$$

where we have rewritten a_1 so that the constant contribution to w is $R\alpha\Delta T(B-l)$. The constant B is chosen so that the boundary condition on w is satisfied on the average:

$$\int_0^l x w(x, l) dx = 0. \quad (14)$$

• Construction of $\eta(x, \zeta)$

We write η in the form

$$\begin{aligned} \eta(x, \zeta) &= 2\mu R^3 \alpha \Delta T \\ &\quad \times \left[\sum_s x J_1(\beta_s x) (A_s \sinh \beta_s \zeta + C_s \cosh \beta_s \zeta) \right. \\ &\quad \left. + \sum_s J_0(\beta_s x) (B_s \sinh \beta_s \zeta + D_s \cosh \beta_s \zeta) \right], \end{aligned} \quad (15)$$

where J_0 and J_1 are Bessel functions and A_s, B_s, C_s, D_s and β_s are constants to be determined. The quantities $J_0(\beta_s x) \times \exp(\pm \beta_s \zeta)$ and $x J_1(\beta_s x) \exp(\pm \beta_s \zeta)$ are well known solutions⁴ of the biharmonic equation (7).

The boundary conditions (6b) on the circumference of the cylinder take the form

$$\sum_s [\gamma_s \cosh \beta_s \zeta + \delta_s \sinh \beta_s \zeta] = 0, \quad (16)$$

where γ_s and δ_s are known in terms of A_s, B_s, C_s and D_s . By expanding this expression in powers of ζ and using the linear independence of various powers of ζ , we obtain a series of homogeneous equations in γ_s or δ_s . We conclude that γ_s and δ_s must vanish if the determinant of coefficients is non-singular. This determinant is of van der Monde

form⁵ and we are thus able to say that Eq. (16) implies $\gamma_s = \delta_s = 0$ if the β_s (which are still to be determined) are such that

$$\prod_{i>j} (\beta_i^2 - \beta_j^2) \neq 0$$

and no β_i is zero or, in other words, if no β is zero or the same as or the negative of another β . [All such cases are readily seen to be redundant: If any β_s is zero, the corresponding terms in Eq. (15) are constants, which can be ignored. Similarly, if any β_s is the same as or the negative of another, it can be eliminated from the sum simply by regrouping terms and redefining the coefficients A_s, B_s, C_s and D_s in Eq. (15)].

We now evaluate T_{rr} and T_{rz} on the circumference. Defining

$$\xi_s \equiv J_0(\beta_s)/J_1(\beta_s) \quad (17)$$

and using the result derived for γ_s and δ_s , we obtain the following equations:

$$\begin{aligned} \left(\frac{K^2}{\beta_s} + \xi_s \right) A_s - B_s &= 0, \\ \left(\frac{K^2}{\beta_s} + \xi_s \right) C_s - D_s &= 0, \\ \left(1 - \frac{\mu}{\lambda + \mu} \frac{\xi_s}{\beta_s} \right) A_s - \left(\frac{1}{\beta_s} - \xi_s \right) B_s &= 0 \text{ and} \\ \left(1 - \frac{\mu}{\lambda + \mu} \frac{\xi_s}{\beta_s} \right) C_s - \left(\frac{1}{\beta_s} - \xi_s \right) D_s &= 0. \end{aligned}$$

These two sets of equations have nontrivial solutions only if

$$\beta_s^2(1 + \xi_s^2) = K^2, \quad (18)$$

in which case

$$\frac{B_s}{A_s} = \frac{D_s}{C_s} = \frac{K^2}{\beta_s} + \xi_s. \quad (19)$$

Equation (18) is the characteristic equation determining the permissible values of β_s over which we sum in Eq. (15) to construct η . Since $1 \leq K^2 \leq 2$ [see Eq. (9) and recall that the value of Poisson's ratio⁶ is between 0 and $\frac{1}{2}$], it is possible to show³ that the β_s 's are complex for all cases of interest. Furthermore, since Bessel functions are real functions and are either symmetric or antisymmetric, it follows that, if β_s satisfies Eq. (18), then β_s^* , $-\beta_s$ and $-\beta_s^*$ also satisfy Eq. (18). (The asterisk denotes complex conjugate.) According to the discussion following Eq. (16), we must omit $-\beta_s$ and $-\beta_s^*$ as well as $\beta_s = 0$, so our sums extend over all β_s (and their conjugates) with positive real part that satisfy Eq. (18).

The function η now takes the form

$$\eta = 2\mu R^3 \alpha \Delta T \sum_s \left[x J_1(\beta_s x) + \left(\frac{K^2}{\beta_s} + \xi_s \right) J_0(\beta_s x) \right] \times (A_s \sinh \beta_s \zeta + C_s \cosh \beta_s \zeta) \quad (20)$$

and the remaining four boundary conditions become

$$\phi_a(x) \equiv \sum_s \beta_s^3 A_s \times \left[\left(\frac{2}{\beta_s} - \xi_s \right) J_0(\beta_s x) - x J_1(\beta_s x) \right] = 0, \quad (21a)$$

$$\phi_b(x) \equiv \sum_s \beta_s^3 C_s [x J_0(\beta_s x) - \xi_s J_1(\beta_s x)] = 0, \quad (21b)$$

$$\phi_c(x) \equiv B + \sum_s \beta_s^2 \left[\left(\frac{K^2}{\beta_s} - \xi_s \right) J_0(\beta_s x) - x J_1(\beta_s x) \right] \times (A_s \sinh \beta_s l + C_s \cosh \beta_s l) = 0, \quad (21c)$$

$$\phi_d(x) \equiv -x + \sum_s \beta_s^2 \left[x J_0(\beta_s x) - \left(\frac{K^2}{\beta_s} + \xi_s \right) J_1(\beta_s x) \right] \times (A_s \cosh \beta_s l + C_s \sinh \beta_s l) = 0, \quad (21d)$$

all for $0 \leq x \leq 1$; these equations are, in order, the conditions that $T_{zz}(x, 0)$, $T_{rz}(x, 0)$, $w(x, l)$ and $u(x, l)$ be zero.

The constant B , which is to be found from Eq. (14), can now be given explicitly in terms of the A_s and C_s ; we obtain

$$B = -2(K^2 - 2) \sum_s J_1(\beta_s) \times (A_s \sinh \beta_s l + C_s \cosh \beta_s l) \quad (22)$$

and $\phi_c(x)$ becomes

$$\phi_c(x) = \sum_s \left\{ 2(2 - K^2) J_1(\beta_s) + \beta_s^2 \left[\left(\frac{K^2}{\beta_s} - \xi_s \right) J_0(\beta_s x) - x J_1(\beta_s x) \right] \right\} \times (A_s \sinh \beta_s l + C_s \cosh \beta_s l). \quad (21c')$$

It is easily verified that

$$\int_0^1 x \left[\left(\frac{2}{\beta_s} - \xi_s \right) J_0(\beta_s x) - x J_1(\beta_s x) \right] dx = 0,$$

which guarantees that Eq. (11) is satisfied. The constants A_s and C_s are both complex; Eqs. (21a) and (21b) furnish relations between their real and imaginary parts rather than a requirement that they be zero. From the structure of Eqs. (21) it is clear that

$$A_s^* \equiv A(\beta_s^*) = [A(\beta_s)]^*$$

and similarly for C_s . Thus all the ϕ 's of Eqs. (21), as well as η itself, are real quantities.

• Least-squares adjustment

The coefficients A_s and C_s have to be determined numerically, since there is not much hope of solving Eqs. (21) analytically. Thus we have to approximate η by a finite number (say $2N$) of terms. To choose the coefficients in the best possible way, subject to this limitation, we minimize the error

$$\epsilon_N = \int_0^1 x(\phi_a^2 + \phi_b^2 + \phi_c^2 + \phi_d^2) dx \quad (23)$$

incurred in trying to satisfy the boundary conditions with a finite number of terms. This procedure is necessary because the functions appearing in Eqs. (21) are not mutually orthogonal.

The minimization conditions

$$\frac{\partial \epsilon_N}{\partial A_s} = \frac{\partial \epsilon_N}{\partial C_s} = 0$$

lead to the linear equations

$$\sum_{s'=1}^{2N} (M_{ss'} A_{s'} + N_{ss'} C_{s'}) = \Gamma_s \cosh \beta_s l, \quad (24)$$

$$\sum_{s'=1}^{2N} (N_{s's} A_{s'} + Q_{s's} C_{s'}) = \Gamma_s \sinh \beta_s l,$$

in which

$$\Gamma_s = J_1(\beta_s) \left(K^2 \xi_s - \frac{4 + K^2}{\beta_s} \right),$$

$$M_{ss'} = \beta_s^2 \beta_{s'}^2 (U_{ss'} \cosh \beta_s l \cosh \beta_{s'} l + V_{ss'} \sinh \beta_s l \sinh \beta_{s'} l + \beta_s \beta_{s'} W_{ss'}), \quad (25)$$

$$N_{ss'} = \beta_s^2 \beta_{s'}^2 (U_{ss'} \cosh \beta_s l \sinh \beta_{s'} l + V_{ss'} \sinh \beta_s l \cosh \beta_{s'} l),$$

$$Q_{ss'} = \beta_s^2 \beta_{s'}^2 (U_{ss'} \sinh \beta_s l \sinh \beta_{s'} l + V_{ss'} \cosh \beta_s l \cosh \beta_{s'} l + \beta_s \beta_{s'} X_{ss'}).$$

The matrices \mathbf{U} , \mathbf{V} , \mathbf{W} and \mathbf{X} , which are linear combinations of integrals of Bessel functions and are independent of l , are discussed further in the Appendix. It is interesting to note that the β_s 's and \mathbf{U} , \mathbf{V} , \mathbf{W} and \mathbf{X} depend only on Poisson's ratio and can be tabulated as functions of this ratio without reference to cylinder dimensions.† Such a tabulation would be of use in solving any problem of cylindrical symmetry in which the circumference is a free surface. Different boundary conditions on the ends of the cylinder will still lead to a set of equations like (24), but with \mathbf{M} , \mathbf{N} and \mathbf{Q} given by different linear combinations of \mathbf{U} , \mathbf{V} , \mathbf{W} and \mathbf{X} .

† Some values of β_s are presented later in Table 1.

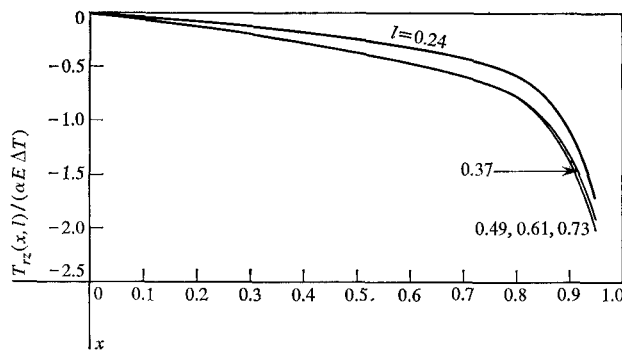


Figure 1 Shear stress on the constrained surface.

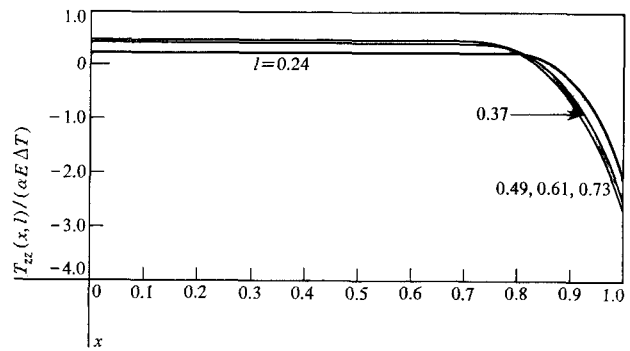


Figure 2 Axial stress on the constrained surface.

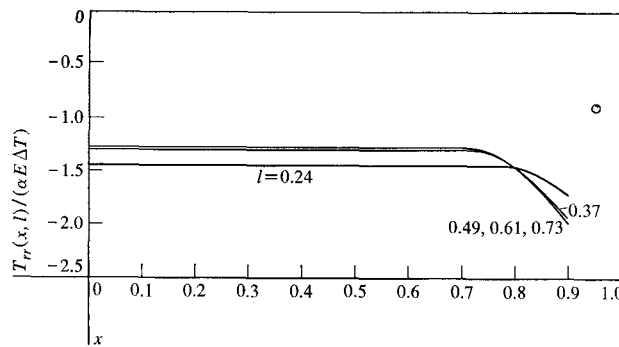


Figure 3 Radial stress on the constrained surface. The encircled point at $x = 0.95$ is the computed value of T_{rr} for $N = 10$; the exact solution should tend to $-\infty$ as $x \rightarrow 1$.

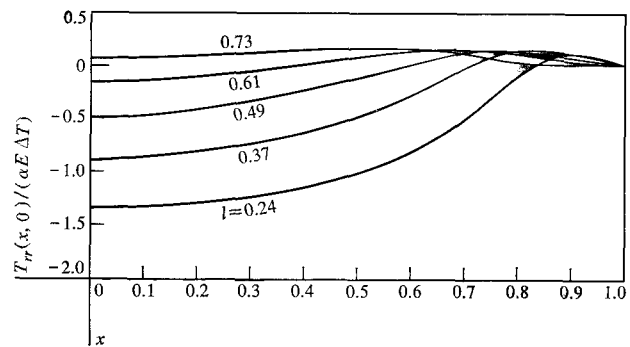


Figure 4 Radial stress on the free end surface.

The $\eta(x, \zeta)$ series is very slowly convergent near $x = 1$, $\zeta = l$ (i.e., near the circumference on the constrained surface) and many more terms would have to be included to improve substantially the results in this neighborhood. It appears, however, that the stress T_{zz} at $x = 1$ and $\zeta = l$ will tend to $-\infty$ as the number of terms becomes sufficiently large (see Fig. 6). Since only $\partial u/\partial z$ and $\partial w/\partial z$ are non-zero on the constrained surface, it follows that $T_{rr}(1, l)$ must also tend to $-\infty$, although the computed values of T_{rr} show no clear indication of this behavior for N less than 10 (see Fig. 3). A similar study of the maximum shear stress on the constrained surface, though more ambiguous, also suggests that $T_{rz}(x, l) \rightarrow -\infty$ as $x \rightarrow 1$ if a sufficiently large number of terms is included. (The presence of stress concentration points at the constrained edges seems to be a general feature of problems of this type.^{1,2}) Because of the lack of orthogonality between the various functions in Eqs. (21), it is not obvious how the convergence can be improved.

In the limit $l \equiv h/R \gg 1$, all stresses vanish on the free surface ($z = 0$) and the stresses on the constrained surface ($z = l$) are much the same as shown in Figs. 1 to 3 for

$l = 0.73$. The axial stress $T_{zz}(1, \zeta)$ is essentially zero unless z is closer than about R to the constrained end (i.e., $\zeta < 1$), where it will behave approximately as shown in Fig. 5. The effects of the constraints, in other words, are negligibly small beyond an axial distance R from the constrained end.

The error ϵ_N , defined in Eq. (23), is shown as a function of N in Fig. 7. This error decreases approximately as $N^{-3/2}$, suggesting that the solution is asymptotically exact as $N \rightarrow \infty$. Values of $T_{zz}(x, 0)$, $T_{rz}(x, 0)$, $w(x, l)$ and $u(x, l)$ for $N = 10$ and $l = 0.73$ are shown in Fig. 8. These quantities should be zero when $N = \infty$, so the figure gives some indication of the convergence that can be obtained with 20 terms in the series (corresponding to 10 roots and their conjugates).

Appendix

The matrices \mathbf{U} , \mathbf{V} , \mathbf{W} and \mathbf{X} were introduced in Eqs. (25). Each of these matrices is defined as an integral over x of the functions obtained by squaring each of Eqs. (21); \mathbf{U} arises from the square of Eq. (21d), \mathbf{V} from (21c), \mathbf{W} from (21a) and \mathbf{X} from (21b).

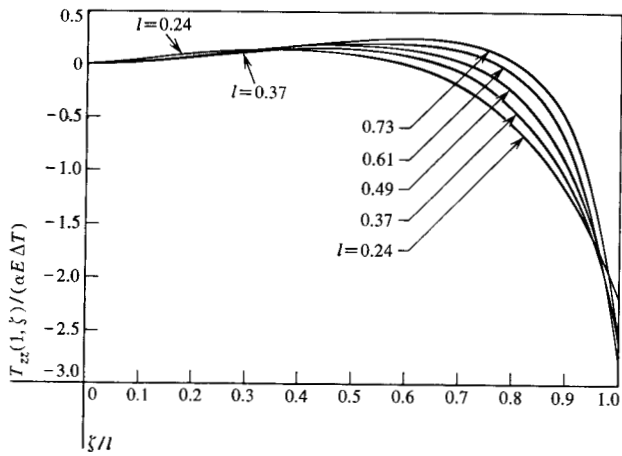


Figure 5 Axial stress on the circumference.

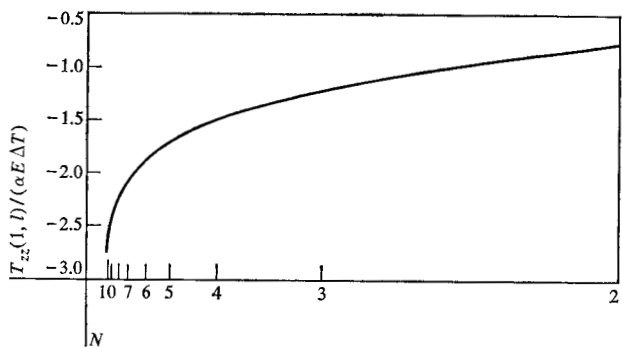


Figure 6 Axial stress at the junction line between cylinder and base as a function of the number of terms in the η series; $l = 0.65$.

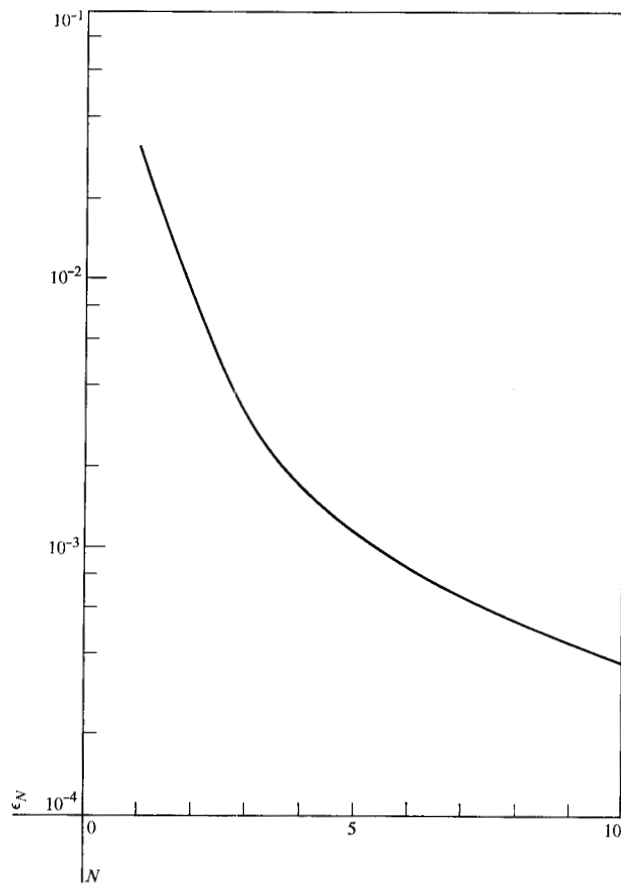
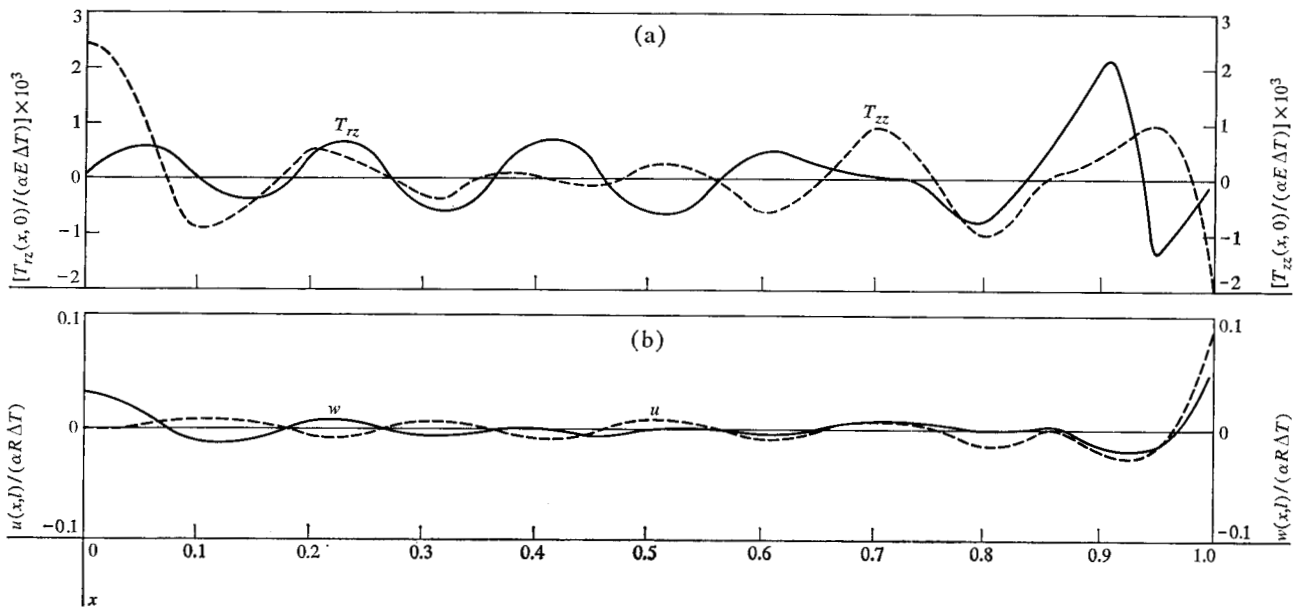


Figure 7 Least-squares error as a function of the number of terms in the η series; $l = 0.65$.

Figure 8 Radial dependence of (a) the shear and axial stresses on the free end surface and (b) the radial and axial displacements on the constrained surface; $l = 0.73$ and $N = 10$.



If we define

$$I_{kl}^{(p)}(ss') = \int_0^1 x^p J_k(\beta_s x) J_l(\beta_{s'} x) dx, \quad (\text{A1})$$

we find

$$\begin{aligned} U_{s's} &= U_{s's} = I_{00}^{(3)}(ss') \\ &\quad - \left(\frac{K^2}{\beta_s} + \xi_s\right) I_{10}^{(2)}(ss') - \left(\frac{K^2}{\beta_{s'}} + \xi_{s'}\right) I_{10}^{(2)}(s's) \\ &\quad + \left(\frac{K^2}{\beta_s} + \xi_s\right) \left(\frac{K^2}{\beta_{s'}} + \xi_{s'}\right) I_{11}^{(1)}(ss'), \end{aligned} \quad (\text{A2})$$

$$\begin{aligned} V_{s's} &= V_{s's} = I_{11}^{(3)}(ss') \\ &\quad - \left(\frac{K^2}{\beta_s} - \xi_s\right) I_{01}^{(2)}(ss') - \left(\frac{K^2}{\beta_{s'}} - \xi_{s'}\right) I_{01}^{(2)}(s's) \\ &\quad + \left(\frac{K^2}{\beta_s} - \xi_s\right) \left(\frac{K^2}{\beta_{s'}} - \xi_{s'}\right) I_{00}^{(1)}(ss') \\ &\quad - \frac{2(2 - K^2)^2}{\beta_s^2 \beta_{s'}^2} J_1(\beta_s) J_1(\beta_{s'}), \end{aligned} \quad (\text{A3})$$

$$\begin{aligned} W_{s's} &= W_{s's} = I_{11}^{(3)}(ss') \\ &\quad - \left(\frac{2}{\beta_s} - \xi_s\right) I_{01}^{(2)}(ss') - \left(\frac{2}{\beta_{s'}} - \xi_{s'}\right) I_{01}^{(2)}(s's) \\ &\quad + \left(\frac{2}{\beta_s} - \xi_s\right) \left(\frac{2}{\beta_{s'}} - \xi_{s'}\right) I_{00}^{(1)}(ss') \text{ and} \end{aligned} \quad (\text{A4})$$

$$\begin{aligned} X_{s's} &= X_{s's} = I_{00}^{(3)}(ss') - \xi_s I_{10}^{(1)}(ss') \\ &\quad - \xi_{s'} I_{10}^{(2)}(s's) + \xi_s \xi_{s'} I_{11}^{(1)}(ss'). \end{aligned} \quad (\text{A5})$$

The quantities $I_{kl}^{(p)}$ can all be obtained by direct integration and one finds

$$I_{00}^{(1)}(ss') = J_1(\beta_s) J_1(\beta_{s'}) (\beta_s \xi_{s'} - \beta_{s'} \xi_s) / (\beta_s^2 - \beta_{s'}^2),$$

$$I_{11}^{(1)}(ss') = J_1(\beta_s) J_1(\beta_{s'}) (\beta_{s'} \xi_s - \beta_s \xi_{s'}) / (\beta_s^2 - \beta_{s'}^2),$$

$$\begin{aligned} I_{10}^{(2)}(ss') &= I_{01}^{(2)}(s's) = [2\beta_s I_{00}^{(1)}(ss') \\ &\quad - J_1(\beta_s) J_1(\beta_{s'}) (\beta_{s'} + \beta_s \xi_s \xi_{s'})] / (\beta_s^2 - \beta_{s'}^2), \end{aligned}$$

$$\begin{aligned} I_{00}^{(3)}(ss') &= I_{00}^{(1)}(ss') \\ &\quad + 2[\beta_{s'} I_{01}^{(2)}(ss') - \beta_s I_{10}^{(2)}(ss')] / (\beta_s^2 - \beta_{s'}^2) \end{aligned}$$

and

$$\begin{aligned} I_{11}^{(3)}(ss') &= I_{11}^{(1)}(ss') \\ &\quad + 2[\beta_s I_{01}^{(2)}(ss') - \beta_{s'} I_{10}^{(2)}(ss')] / (\beta_s^2 - \beta_{s'}^2). \end{aligned}$$

Thus the matrices **U**, **V**, **W** and **X** can be constructed once a tabulation of β_s , ξ_s and $J_1(\beta_s)$ is available. These matrices depend only on the parameter K^2 and are independent of the dimensions of the cylinder.

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